

## Section 3D. Coefficient Uncertainty

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## Coefficients Accuracy

- ▶ Assume that we observe data generated by an additive linear model of the form

$$\mathbf{x}_i \sim f_X \text{ and } \mathbf{y} = M_X \beta + \varepsilon, \text{ where } \varepsilon_i \sim f_\varepsilon$$

- ▶ We can estimate the linear coefficients as  $\hat{\beta} = (M_X^\top M_X)^{-1} M_X^\top \mathbf{y}$ . Note that, since the datapoints  $(\mathbf{x}_i, y_i)$  are random, *the coefficients  $\hat{\beta}_i$  are random variables themselves!*
- ▶ **Mean analysis:** One can prove that  $\mathbb{E} [\hat{\beta}_i] = \beta_i$  for all  $i$  (unbiased estimator)
- ▶ **Covariance analysis:** Assuming that we are given a data matrix  $M_X$ , the covariance matrix of  $\hat{\beta}$  satisfies (without proof)

$$\text{Cov} [\hat{\beta} | M_X] = \sigma^2 (M_X^\top M_X)^{-1}$$

## Coefficients Accuracy: Univariate Case

- ▶ For the particular case  $p = 1$ , the linear regression takes the form  $\hat{Y} = \hat{\beta}_0 + \hat{\beta}_1 X$
- ▶ The diagonal elements of the covariance matrix are the variances of the estimated coefficients. These variances are:

$$\text{SD}(\hat{\beta}_1)^2 = \text{Var}[\hat{\beta}_1 | \{x_i\}_{i=1}^N] = \frac{\sigma^2}{\sum_{i=1}^N (x_i - \bar{x})^2}$$

$$\text{SD}(\hat{\beta}_0)^2 = \text{Var}[\hat{\beta}_0 | \{x_i\}_{i=1}^N] = \sigma^2 \left( \frac{1}{N} + \frac{\bar{x}^2}{\sum_{i=1}^N (x_i - \bar{x})^2} \right)$$

with  $\sigma^2 = \text{Var}(\varepsilon)$ ,  $\bar{y} = \frac{1}{N} \sum_{i=1}^N y_i$  and  $\bar{x} = \frac{1}{N} \sum_{i=1}^N x_i$ . In this course, we use  $\text{SD}(\cdot)$  to denote the Standard Deviation of a r.v.

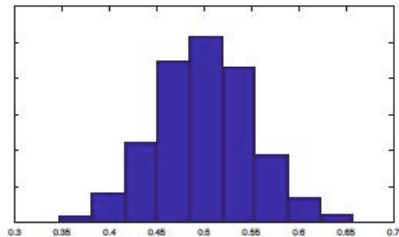
## Coefficients Accuracy: Numerical Example

**Numerical validation:** Let us consider an unrealistic, but illustrative situation

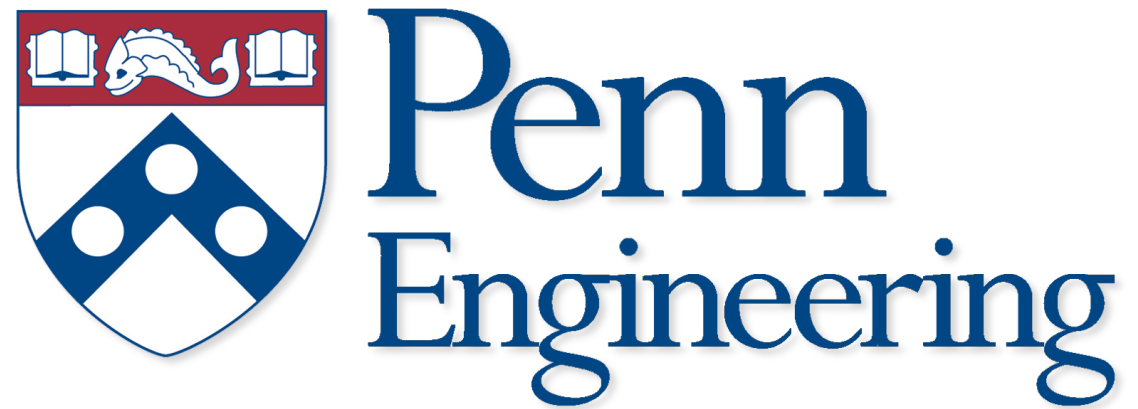
- ▶ Consider 1,000 independent realizations of a training dataset,  $\mathcal{D}_{\text{Tr}}^k$  for  $k = 1, 2, \dots, 1000$ . Notice that, in practice, we will only have access to a single realization of a training dataset!
- ▶ Each dataset contains  $N = 100$  sample points  $\mathcal{D}_{\text{Tr}}^k = \{(\mathbf{x}_1^k, y_1^k), \dots, (\mathbf{x}_{100}^k, y_{100}^k)\}$
- ▶ For each  $\mathcal{D}_{\text{Tr}}^k$ , we compute the corresponding estimates  $\hat{\beta}_0^k$  and  $\hat{\beta}_1^k$  for  $k = 1, 2, \dots, 1000$

## Coefficients Accuracy: Numerical Example

In this example,  $\beta_1 = \mathbb{E}[\hat{\beta}_1] = 0.5$  and  $\text{Var}[\hat{\beta}_1 | \text{var}(N)] = 0.052$



**Figure:** Histogram of the values of  $\hat{\beta}_1^k$ . We have used a linear model  $Y = 1 + 0.5X + \varepsilon$ , where  $X \sim \mathcal{N}(0, 1)$  and  $\text{Var}(\varepsilon) = \sigma^2 = 1$ .



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